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Characterizing air traffic networks via large-scale aircraft tracking data: A comparison between China and the US networks

Pan Ren, Lishuai Li

ABSTRACT

Air travel demand has continued to increase rapidly over the past decade, causing severe flight delays. To reduce such delays, Air Navigation Service Providers need to first understand the operational capacity and congestion risks associated with a network, and then develop strategies accordingly. However, limited studies have been conducted due to lack of data. New opportunities have arisen given the availability of large-scale aircraft tracking data and many other digitalized records of operations. In response, we develop a novel data-driven framework that characterizes the operational structure and dynamics of an air traffic network using actual tracking data. The framework includes several new statistical measures and data analytic techniques to summarize airspace availability, network structure, and utilization patterns. We then apply the framework to analyze the air traffic networks in China and the US. The results reveal distinctive characteristics of these two networks.

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Data analytics

1. Introduction

Air transport system capacity enhancements have failed to keep up with the increasing pace of demand growth all over the world, causing severe air traffic congestion and flight delays, which have had high economic costs and negative environmental effects (Ball et al., 2010). To reduce these delays, it is critical to understand the operational capacity, efficiency, and congestion risks associated with an air transport network, and to carry out strategic planning and tactical management interventions accordingly to mitigate these issues.

Despite extensive studies on air transport network, few research has been done to characterize the operational structure and dynamics of national-level air traffic networks, or compare how air space is managed between different regions based on actual air traffic flows. A key limitation lies in the availability of operational data across different sources and regions. For example, aircraft tracks, air traffic control commands, fleet scheduling, data were heavily regulated by national or regional agencies and airlines without proper information sharing among them. Air traffic service providers can rarely grasp a ‘big picture’ of the regional airspace.

New opportunities have arisen from the increasing availability of digitized air traffic data. For example, with the implementation of Automatic Dependent Surveillance – Broadcast (ADS-B), a satellite-based surveillance technology that tracks and broadcasts the location of each aircraft via satellite, it is now possible to track and analyze aircraft movement data on a global scale. With the appropriate analytical tools, post-event analysis can be carried out to examine the characteristics of the actual air traffic network.

Thus, the development of analytical tools to analyze large-scale multi-source operational data can significantly contribute to the improvement of air transport system. To support this effort, in this study, we aim to characterize the structure and dynamics of the air traffic network via a data-driven approach using large-scale aircraft tracking data. The analysis result will allow Air Navigation Service Providers (ANSP) to understand the current network better, identify deficiencies in Air Traffic Management (ATM) procedures, and provide recommendations for improving system capacity and efficiency.

Relevant literature exists in two groups. The first group of research focus on understanding the air transport system using network analysis, in which the air transport system is considered as a complex network...
composed of many interlinked subsystems. Some of these studies use complex network theory to analyze the topological characteristics of the system (Guimerà et al., 2005; Vespignani, 2012; Cook et al., 2015; He et al., 2004; Li and Cai, 2004). In these studies, the air transport system is abstracted to a directed/undirected, weighted/unweighted network, where nodes are represented by airports and edges are direct flights linking two airports. The network is evaluated and optimized using the robustness metrics in network theory, which include betweenness, degree, centrality, and connectivity (DeLaurentis et al., 2008). Wei et al. (2014) developed a data mining framework to analyze an air traffic network by maximizing algebraic connectivity to reduce air traffic congestion. However, these studies only considered a static graph, meaning that the dynamics of the network were not explicitly considered. To address this limitation, other studies have focused on studying how delays propagate in the network. Empirical studies using flight schedule and delay data have analyzed the causes for primary delays and assessed how they spread over the network, causing reactionary delays (Beatty et al., 1999; Fricke and Schultz, 2009; Hansen, 2002; Abdelghany et al., 2004; Jetzki, 2009; Rebollo and Balakrishnan, 2014). Furthermore, Fleurquin et al. (2013) defined metrics that quantify the level of network congestion and the macro-scale behavior of delay dynamics. Péter and Szabó (2012) proposed an exact mathematical model for large-scale dynamic networks from the perspective of control theory using a class of positive systems, which could be used to achieve minimized delays. Another stream of studies used queueing theory to model and simulate flight delays within a network (Pyrgiotis et al., 2013; Hansen et al., 2009; Long and Hasan, 2009; Peterson et al., 1995a, 1995b; Xu, 2007; Shah et al., 2005); however, the performance of these models relies on how well the underlying conceptual network can represent real air traffic operations.

Recent studies suggest that representing air transport systems as airport networks is an oversimplified approach, as it discards important operational information of ATM (i.e., flow management). Some scholars propose that the air transport network can be regarded as aggregated multi-layers of airline networks (Zanin and Lillo, 2013; Du et al., 2016; Belkoura et al., 2016), airport networks, air navigation route networks (Sun et al., 2015), and air traffic management networks (Wang et al., 2017). Although the findings of these studies helped to better conceptualize the complexity of air transport systems, there is much work to be done to obtain a more comprehensive picture. One drawback associated with the current work on multi-layer air transport networks is that this endeavor requires a significant amount of detailed information from ANSP and airlines that can construct the different layers of the system, such as air route information, sector maps, letter of agreements (LOA), airline route networks, and so on; this makes it cumbersome to use across the air transport networks of different regions.

The second group of relevant research focus on how to analyze and use large-scale air traffic operational data. Several studies have been carried out that use clustering techniques on actual tracking data for air traffic flow identification. Eckstein (2009) developed a flight track taxonomy to decompose a set of radar tracks according to their lateral, vertical, and conformance segments, for the purpose of evaluating procedural conformance of individual flights in the terminal airspace. Gariel et al. (2011) developed an analytical framework that uses density-based clustering to learn the typical patterns of traffic flows, which are then used as benchmarks to monitor the behavior of an aircraft in a given airspace. Other studies use hierarchical or spectral clustering to identify air traffic flows to and from an airport (Rehm, 2010; Enriquez, 2013). Nevertheless, these studies focused on flow identification on a relatively small scale – i.e., at the terminal area or by examining flows to and from an airport, without further analysis on ATM operations. The exception to this is the work of Conde Rocha Murca et al. (2016), as this research team stepped forward along the direction of characterizing large-scale ATM operations. The authors developed a data mining framework to characterize the air traffic flows in the transition/terminal airspace, and demonstrated how to use the results to assess the performance of tactical operations in the New York region on a daily basis.

In summary, further research is needed to study the air transport system, understand its network's structure and dynamics at different scales, and ensure that the analysis results are useful for ATM improvement. The availability of large-scale operational data and the advancements in data mining techniques have created unprecedented opportunities for such research. The aim of this investigation is thus to develop a data-driven framework to analyze an air traffic network using aircraft-tracking data, including route availability, network structure, and utilization patterns. The framework includes an innovative statistical measure – a modified Ripley’s K-function – to assess air route availability, clustering techniques to identify major air routes, network analysis to quantify the actual air traffic network structure, and spatial–temporal analysis to reveal airspace utilization patterns. In order to demonstrate the proposed framework, we apply it to analyze and compare the air traffic networks in China and the US using one month of historical flight-tracking data.

The remainder of this paper is organized as follows. Section 2 describes the aircraft-tracking data used in this study. Section 3 presents the proposed data-driven framework, including the algorithms and metrics used in each module of the framework. In Section 4, we conduct a comparative study of China and the US airspaces using the proposed framework. Finally, Section 5 summarizes our study and suggests some future research directions.

2. Dataset

Automatic Dependent Surveillance – Broadcast (ADS-B) is a key component of the US Next Generation Air Transportation System (NextGen) and it enables aircraft to track their positions and broadcast them via satellites (Gugliotta, 2009). ADS-B greatly enhances the safety of air travel by not only providing air traffic control with real-time, consistent, and visible position updates, but it also notes other aircraft equipped with ADS-B. Currently, 70% of all commercial passenger aircraft are equipped with an ADS-B transponder and the percentage is steadily increasing, as the ADS-B transponder will become mandatory for most aircraft around the world by 2020 (Flighttrader24, 2015). Air traffic management decision makers can benefit significantly from such data when engaging in performance assessments, real-time monitoring, and strategic planning. Currently, several flight-tracking service providers operate a worldwide network of ADS-B receivers to collect and share live flight tracks, such as Flighttrader24 and FlightAware.

The dataset used in this study features flight-tracking data collected from Flighttrader24 every minute for 30 consecutive days, from November 1 to November 30, 2016, covering the airspace in China and the US. The geographic ranges of the airspace in China and the US are set as (17.37, 46.00, 92.86, 126.50) and (24.80, 49.20, −124.90, −60.40), respectively. The first two values are the boundary latitudes, while the last two values are the boundary longitudes. Fig. 1 shows all flight trajectories collected. For this research, we focus on air traffic networks consisting of the top 10 busiest airports in China and the US, as ranked by annual passenger traffic (CAAC, 2015a; ACI-NA, 2015). The information related to these airports is presented in Appendix A. In addition, we filter out airport pairs where the sample size is less than one flight per day. As a result, 40 airport pairs in China and 45 airport pairs in the US are left in our analysis. The flight trajectories of top 10 airports in China and the US are visualized in Fig. 2.

We choose to compare the air traffic network in China and the US because: 1) they are the busiest two regions in the world (ranked by passengers carried in 2015 (WBG, 2015)); 2) both are faced with significant flight delays (in 2015, 18.27% of flights were delayed and the average delay time relative to scheduled time was 11 min in the US (BTS, 2015), while 31.67% of flights were delayed and the average delay time was 21 min in China (CAAC, 2015b)); and 3) the airspaces
are managed differently, which can result in distinctive air traffic network characteristics – i.e., 80% of China’s national airspace is devoted to military use, while the US military only controls 20% of the US airspace, primarily over remote or ocean areas (Hsu, 2014).

3. Methodology

A new data-driven framework is proposed to characterize the operations of a national air traffic network based on ADS-B data. The framework consists of three parts in sequence: Part 1 quantifies airspace route availability; Part 2 analyzes air traffic network structure; and Part 3 reveals network utilization patterns. Fig. 3 provides an overview of the framework; it shows the sequence of the three parts, the analysis and results associated with each part, and demonstrates how they are interrelated. The details of each part are described in the following subsections.

3.1. Quantify airspace route availability

3.1.1. Filtering and resampling

The raw ADS-B data may contain incomplete flight tracks that do not link to an origin or a destination airport due to ADS-B receiver coverage limitations. Therefore, data filtering is performed to filter out the incomplete flight tracks based on the following rules: If the distance between the start point of a flight track and its associated origin airport is greater than 25 miles, or if the distance between the end point of a flight track and its associated destination airport is greater than 25 miles, the flight track is considered incomplete and is excluded from our analysis.

Then, resampling is performed to convert all raw flight tracks into time series with the same length of $N$ data points. A raw flight track is represented by a vector, $F_i = \{x_{i1}, x_{i2}, x_{i3}, \ldots, x_{iN}\}$, where $F_i$ represents Flight $i$, $x_{ij}$ is the geographic coordinates of the $j$-th data point of $F_i$, and $N_i$ is the original data length of $F_i$. $N$ equals the average value of $N_i$ across all flights with an origin and destination (OD) pair. The detailed resampling procedure is as follows:

- Step 1: Set the link between the origin airport and destination airport of $F_i$ as the benchmark line, represented by OD.
- Step 2: Divide the OD line into $(N-1)$ equal parts to get $N$ benchmark points, including the start point (origin airport) and end point (destination airport).
- Step 3: Draw perpendicular lines of the OD line through each benchmark point, $P_i$.
- Step 4: Find the intersecting point between each perpendicular line and flight track $F_i$; these points constitute the resampled flight track, denoted as $F'_i = \{x'_{i1}, x'_{i2}, \ldots, x'_{iN}\}$.

Fig. 4 illustrates the resampling method.

3.1.2. Modified Ripley’s K-function

To measure air route availability in a specific airspace, we propose a new statistical measure, a modified Ripley’s K-function. Air route availability is one of the factors that determine airspace capacity. An airspace with more space for commercial flights generally allows more routing choices and faces fewer opportunities for en-route congestion. For example, Fig. 5 shows the flight tracks between two airport pairs: 1) Guangzhou Baiyun International Airport (CAN) and Chengdu Shuangliu International Airport (CTU) in China and 2) Dallas/Fort Worth International Airport (DFW) and Chicago O’Hare International Airport (ORD) in the US. The distance and number of flights are similar in the two airport pairs; however, the air route availability is different. Flights between CAN and CTU only have one routing choice, with some deviations when cruising through the airspace; therefore, it has a higher chance of being congested, especially under convective weather impact.

Such differences in air route availability are visually apparent, yet challenging to quantify. Simple trajectory clustering to identify major routing choices will not work because airspaces of difference sizes cannot be compared fairly. In this paper, we measure air route availability via two approaches: 1) simple descriptive statistics of Euclidean distance between flight tracks by airport pair; and 2) a scale-free indicator, the modified Ripley’s K function, to measure how dispersed/concentrated flight tracks are in a specified airspace.

A modified Euclidean distance between flight tracks by airport pair is calculated using the following equation:

$$D(i, j) = \frac{\sum_{k} \text{dis}(x_{ik}, x'_{jk})}{N}$$

(1)

where $x_{ik}$ is the $k$-th geographic coordinate vector of flight $F_i$, $x'_{jk}$ is the $k$-th geographic coordinate vector of flight $F'_j$, $N$ is the sample size of

Fig. 2. Flight trajectories of the top 10 airports in China and the US.
each resampled flight track, and \( \text{dis}(x_{ik}', x_{jk}') \) is the great-circle distance between trajectory points \( x_{ik}' \) and \( x_{jk}' \). Flight \( F_i \) and flight \( F_j \) belong to the same airport pair. To compare different airport pairs fairly, the Euclidean distance between two flight tracks is standardized as standardized neighborhood distance (SND) by a factor of \( D_{OD} \), which is the great circle distance between the origin and destination airport. The SND is calculated as

\[
\text{SND}_d = \frac{\sum \text{dis}(x_{ik}', x_{jk}')}{N_d D_{OD}}
\]

(2)

The Ripley’s K-function is a widely used spatial analysis method that is employed to describe the distribution pattern of points over a given region of interest (Haase, 1995; Dixon, 2002). It allows researchers to determine whether the points appear to be dispersed, clustered, or randomly distributed throughout the study region. The function counts the number of neighboring points found within a given distance for each individual point; its formula (Haase, 1995) is as follows:

\[
K(t) = \lambda^{-1} \sum_{i \neq j} I(d_{ij} < t)/n
\]

(3)

where \( d_{ij} \) is the Euclidean distance between the \( i \)-th and \( j \)-th points in a dataset of \( n \) points, \( I \) equals 1 if \( d_{ij} < t \) (the radius of the circle),
otherwise it equals to 0 and $\lambda$ is the density of points (generally estimated as $n/A$, where $A$ is the area of the region contains all points). Fig. 6 indicates two typical flight trajectory distribution patterns. The Ripley's K-function curve of randomly distributed points tends to be steadier than clustered points.

Here, we extend Ripley's K function to describe the spatial distribution patterns of flight trajectories in the specified airspace. The formula is modified as:

$$K(r) = \sum_{m=1}^{N_m} \sum_{j=1}^{N_m} h_i(SND_{ij}) \quad \text{for all } m, r$$

where $N_m$ is the number of flight tracks in airport pair $m$, $r$ is a given neighborhood distance, and $h_i(SND_{ij})$ equals 1 if $SND_{ij} < r$, and 0 otherwise.

The new Ripley's K-function computes the percentage of neighboring flight tracks within a given distance of each flight track. Fig. 7 indicates three typical distribution patterns of flight tracks between two airports, which are: Class 1—distributed in several clusters, Class 2—concentrated in one cluster, and Class 3—dispersed.

We propose a method to classify these three typical patterns based on the properties of K-function curves. First, to identify Class 1 cases, where the trajectories are distributed in several clusters, we identify the inflection points of the K-function curve, which are the points at which the curve changes from being convex to concave, or vice versa, indicating the number of neighboring flight track stops or starts increasing with distance $r$. Two criteria are applied successively to identify Class 1 cases. First, there must be at least two inflection points. Second, the distance between two consecutive inflection points, which is calculated as $SND_{*}D_{OD}$, must be greater than 10 nm (width of an airway) to ensure that the gap between clusters of flight tracks is significant enough. Fig. 8 shows the inflections of K-function curves for three cases. In the left panel, there are three inflection points, and the distances between all consecutive points are greater than 10 nm; therefore, the distribution of flight tracks in this airport pair would be identified as Class 1. In the center panel, even though there are six inflection points, the distances between all consecutive pairs are less than 10 nm. In the right panel, there is only one inflection point. For the central and right panels, these cases cannot be classified into Class 1. Additional information needs to be verified in order to group them into either Class 2 or 3.

Then, to distinguish between Classes 2 and 3, we check the value of $r$ when $K(r)$ equals 0.9 ($r_{0.9}$) and compare it with a threshold value. $r_{0.9}$ represents the SND that covers 90% of flight tracks in an airport pair. When $r_{0.9}$ is less than the threshold value, we consider that the flight tracks are concentrated in a single cluster and are classified as Class 2; otherwise, flight tracks are dispersed and classified as Class 3. The threshold value is determined by sensitivity analysis. We

![Fig. 6. Typical point distribution patterns and the corresponding K-function curves.](image)

![Fig. 7. Typical distribution patterns of flight tracks and the corresponding K-function curves.](image)
Section 3.2: Analyze air traffic network structure

The second part of the framework focuses on characterizing network structure based on actual air traffic flows. Trajectory clustering and air route merging is first performed to identify the network structure of national-level air traffic flows. Network analysis is then conducted to evaluate the features of real network operations, including centrality, transport efficiency, connectivity, and robustness.

3.2.1. Trajectory clustering

Cluster analysis is performed on flight tracks by airport pair to better understand the air routes used by actual flights, without any prior knowledge of airspace structure. These air routes are then used to construct an operational air traffic network. Cluster analysis is a commonly used data-mining technique that can identify common groups of observations in a dataset. Many clustering algorithms have been developed for different purposes. Here, we use a clustering algorithm called Density-Based Spatial Clustering of Applications with Noise (DBSCAN) (Ester et al., 1996). The basic idea of DBSCAN is to progressively find density-connected points to form a cluster. If at least Minpt points lie within a ball of radius centered at a point, a cluster is then created. Two unique features of DBSCAN make it suitable for this problem: 1) it can automatically determine the number of clusters; and 2) it can handle data with outliers. In this problem, the number of air routes may not be the same across different airport pairs, and this number is unknown without prior knowledge of airspace structures. Using DBSCAN, this number can be automatically determined based on data distribution patterns. Abnormal flight tracks can emerge due to vectoring or under other special conditions, which can be treated as outliers in DBSCAN. Several studies have shown that DBSCAN is an effective technique for identifying the norms of operations in air transportation systems (Gariel et al., 2011; Li et al., 2015; Conde Rocha Murca et al., 2016).

Two key input parameters, Minpt and Epsilon, may result in changes to the clustering solution. Epsilon is the maximum radius of neighborhood distance between points and Minpt is the minimum number of points in an Epsilon neighborhood. For our dataset, the clustering result is not sensitive to Minpts when it is between 3 and 10, so we set Minpt as 5 for all cases. The value of Epsilon is set differently for each airport pair to find the best result that matches the distribution pattern. We compute the k-nearest neighbor distances – where k equals Minpt – plot these k-distances in a descending order for all data points, and find the first “valley” of the sorted k-distance graph (Ester et al., 1996). This “valley” point corresponds to a threshold point where a sharp change in the gradient occurs along the k-distance curve, representing a change in density distribution amongst data points. The k-distance value of the threshold point is used as the Epsilon value for DBSCAN (Ester et al., 1996).

3.2.2. Air route merging

We should note that the air routes generated via trajectory clustering cannot be directly used to construct the air traffic network, as the same airspace resource used by different airport pairs could be identified as multiple air routes, particularly since the clustering is performed by airport pair. For example, as shown in Fig. 10A, the air route depicted in red linking Chengdu Shuangliu International Airport (CTU) and Beijing Capital International Airport (PEK) shares the same en-route airspace resource with two other airport pairs: the air route in blue that links CTU and Xi’an Xianyang International Airport (XIY) (blue line) and the one in green that links XIY and PEK. Fig. 10B shows another example: the air route between Hong Kong International Airport (HKG) and PEK (blue line) shares the same en-route airspace resource with the air route between Shenzhen Bao’an International Airport (SZX) and PEK (red line).

To ensure the reality of air route structure reflected in the network that we construct from the ADS-B data, we develop a procedure to merge air routes using the same airspace resource after the trajectory clustering. For each air route identified from trajectory clustering, we evaluate whether it should be merged with any other route. The merge criteria are: If the Euclidean distance between one air route and

* The Euclidean distance is calculated as \( \sum_k d(x_k, \bar{x}_k)/N \), where \( x_k \) is the k-th point
another is less than 25 nm, this air route is deleted and the traffic load on it is merged with the other. The pseudo code of the air route merge procedure is shown as follows:

Air route merging procedure
1  Input: Air route set AR, Air route traffic load set T
2  Start
3  for each air route ar in air route set AR
4      if ar has been visited
5          continue next air route
6      else
7          Mark ar as visited
8          for each other air route ar in AR
9              if (distance(ar, ar')<25nm)
10                     lr=Max(ar, ar') # The longer air route
11                     sr=Min(ar, ar') # The shorter air route
12                     Tr= Tr + lr # Combine traffic load on sr and lr to sr
13                     Split lr into 3 segments by using airports of sr as split-point
14                     Delete lr from air route set AR
15                     Delete the segment sharing the same airspace resource with sr
16                     for each other segment
17                           if (length(segment)>100nm) # Enough to be a new route
18                              Add it to air route set AR as a new air route
19                              Tnew= Tnew + lr # Assign traffic load on lr to new air route
20                     end
21                     end
22                     break
23                     end
24  End
25  Output: Updated air route set AR', Updated traffic load set T'

Image 1

3.2.3. Network structure analysis

After the air routes are identified by cluster analysis and merged using the merging procedure, we construct an undirected weighted network and apply network analysis to assess its structural features. We denote the air traffic network as $G(V, E)$, where node set $V$ represents airports and edge set $E$ represents the links between two airports. The adjacency matrix of the air traffic network consisting of $N_{airport}$ airports is defined by a $N_{airport} \times N_{airport}$ binary matrix $A = \{a_{ij}\}$, whose element $a_{ij}$ equals 1 when there is at least one air route (after merging procedure) connecting airport $i$ to airport $j$, and 0 otherwise ($i, j = 1, 2, \ldots, N_{airport}$). Weights of edges are represented by weight matrix $W = \{w_{ij}\}$, where $w_{ij}$ is defined by the number of air routes (after the merging procedure) linking airport $i$ and airport $j$.

Several metrics are available for the network structure assessment. Here, we choose three commonly used metrics to evaluate the heterogeneity among nodes, the efficiency of transport on a network, and the resilience of a network.
1) Weighted degree centrality

The weighted degree centrality is a measure of the strength of vertices in a network. The node degree is extended to the strength degree for a weighted network, which is the sum of the weights of all links attached to node \( i \) (Barrat et al., 2004). The strength degree of airport \( i \) in the air traffic network is defined as:

\[
s_i = \sum_{j=1}^{N_{\text{airport}}} d_{ij} W_{ij}
\]

(5)

The degree centrality of the air traffic network is calculated as:

\[
S = \frac{1}{N_{\text{airport}}} \sum_{j=1}^{N_{\text{airport}}} s_i
\]

(6)

And the standard deviation of weighted degree centrality is calculated as:

\[
S_{\text{sd}} = \sqrt{\frac{1}{N_{\text{airport}}} \sum_{j=1}^{N_{\text{airport}}} (s_i - \bar{s})^2}
\]

(7)

2) Characteristic path length

The characteristic path length measures the efficiency of information or mass transporting on a network, which is defined as the average of the shortest path lengths between any two nodes of a network. Since a higher weight \( w_{ij} \) implies more available air routes between airport \( i \) and airport \( j \) in the air traffic network, the path length between airport \( i \) and airport \( j \) is therefore shorter. Consequently, the shortest path length is defined as the smallest sum of the inverse weights of the links throughout all possible paths from node \( i \) to node \( j \) (Newman, 2001), which is calculated as:

\[
S_{\text{dj}} = \min_{\gamma(i,j) \in \Gamma(i,j)} \sum_{m,n \in \gamma(i,j)} \frac{1}{w_{mn}}
\]

(8)

where \( \gamma(i,j) \) is a path from node \( i \) to node \( j \), \( \Gamma(i,j) \) is the class of all possible paths from \( i \) to \( j \), and \( m \) and \( n \) are the points along the path \( \gamma(i,j) \). The characteristic path length of the air traffic network is defined as:

\[
P = \frac{2}{N_{\text{airport}}(N_{\text{airport}} - 1)} \sum_{i,j} S_{\text{dj}}
\]

(9)

When there are more air routes linking two airports, the shortest path length is smaller, more routing choices are available, and more traffic throughput per unit of time is possible; therefore, a network with a smaller characteristic path length facilitates more efficient and rapid flight movements.

3) Algebraic connectivity

Algebraic connectivity is calculated as the second smallest eigenvalue of the Laplacian matrix for a weighted network (Fiedler, 1989). The Laplacian matrix is defined as \( L = (l_{ij}) = D - W \), where \( D \) is the degree matrix, \( W \) is the weight matrix, and \( l_{ij} \) is the Laplacian distance between node \( i \) and node \( j \), which is calculated as:

\[
l_{ij} = \begin{cases} -w_{ij} & \text{if } i \neq j \\ \sum_{i=1}^{n} w_{ij} & \text{if } i = j \end{cases}
\]

(10)

Since the second smallest eigenvalue of \( L \) serves as a lower bound of node connectivity and edge connectivity, the algebraic connectivity is very important when measuring the robustness of a network to node and its edge failures; in this sense, the larger the algebraic connectivity, the more difficult it is to cut a graph into independent components, which means that this network is increasingly more robust.

3.3. Reveal network utilization patterns

The last part of the framework aims to reveal the utilization pattern of the air traffic network based on actual traffic flow data. The constructed air traffic network from previous steps represents the static structure of a national air traffic network. From an operational perspective, we would also like to understand the utilization dynamics of this air traffic network to answer questions such as, “Which are the busy or rarely used air routes?”, “Are there any typical patterns in selecting which air routes to use during different times of the day or under light/ heavy traffic demand?”, etc.

To reveal such network utilization patterns, we perform a spatial-temporal analysis by constructing a Network Traffic Load Matrix, which is denoted as \( \text{NTLM} = \{n_{ij}\} \); elements \( n_{ij} \) are equal to the number of flights traveling along air route \( j \) in hour \( i \), if this air route is used, otherwise it equals 0. Each row of \( \text{NTLM} \) reflects the distribution of traffic load across air routes in a given hour, while each column gives the traffic load on an air route across the hours included in the analysis. Cluster analysis is performed on both the rows and columns to identify the typical utilization patterns and groups of air routes that share similar usage patterns.

4. Results

4.1. Data filtering

Following a data filtering, about 90% of the flights in the 40 airport pairs in China are recognized as complete flights, and 72% of the flights in the 45 airport pairs in the US are recognized as complete flights. Table 1 shows the detailed numbers.

4.2. Results of airspace route availability

4.2.1. Statistics on Euclidean distance between flight tracks by airport pair

Within each airport pair, we calculate the modified Euclidean distance of all pairs of trajectories following Equation (1), and record four statistical measures: the maximum value, minimum value, mean value, and standard deviation. The maximum value reflects the distance between the two furthest points on two flight trajectories, while the minimum value measures the distance between the two nearest trajectories. To summarize the entire air traffic network, we calculate the average values of these four measures over all airport pairs, and the results are shown in Table 2; for example, column 3 shows the mean value of pairwise distance between trajectories, which implies that the average Euclidean distance between a pair of tracks connecting any particular airport pair in China (the US) is equal to 25.29 nm (54.60 nm).

Table 1

<table>
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<th></th>
<th>China (40 airport pairs)</th>
<th>United States (45 airport pairs)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of original flights</td>
<td>42,815</td>
<td>48,797</td>
</tr>
<tr>
<td>Number of complete flights</td>
<td>38,420</td>
<td>35,058</td>
</tr>
<tr>
<td>Percentage of complete flights</td>
<td>90%</td>
<td>72%</td>
</tr>
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Table 2

<table>
<thead>
<tr>
<th></th>
<th>Max</th>
<th>Min</th>
<th>Mean</th>
<th>Std</th>
</tr>
</thead>
<tbody>
<tr>
<td>China</td>
<td>99.56</td>
<td>0.43</td>
<td>25.29</td>
<td>18.64</td>
</tr>
<tr>
<td>United States</td>
<td>269.86</td>
<td>0.19</td>
<td>54.60</td>
<td>41.13</td>
</tr>
</tbody>
</table>
As shown in Table 2, and except for the minimum value, the US has larger values than China on the remaining three measures. Both the maximum and mean values of the pairwise distance reflect how much airspace is available for flight tracks between two airports. The results demonstrate that airspace availability is much larger in the US than in China. The standard deviation is also larger in the US, which means that the variation of distances between flight tracks is larger in the US than in China. The minimum value is lower in the US than in China, which shows that it is rare to have two flights flying on the exact same track in China. The potential reasons for this could be the implementation of a less advanced navigation system and/or different air traffic procedures. The key finding from this result is that flight tracks within each airport pair are much more concentrated in China than in the US, indicating a more restricted airspace for commercial flights in China.

4.2.2. Distribution patterns of flight tracks based on a modified Ripley’s K function

Given the standardized neighborhood distance of flight tracks, we obtain the modified Ripley’s K-function curve of flight track distribution in each airport pair in China and the US, as shown in Fig. 11. These K curves are classified based on the criteria proposed in Section 3.1.2., whereby the different cases were categorized into three classes: Class 1 (in blue): distributed in several clusters; Class 2 (in yellow): concentrated in one cluster; and Class 3 (in red): dispersed. Fig. 12 shows examples of real flight tracks of three distribution types and the corresponding K curves.

The classification results of K-function curves for China and the US are listed in Table 3. Flight tracks in most airport pairs in China are identified as clustered, while flight tracks in the US are more dispersed.

Both the Euclidean distance analysis and modified Ripley’s K-function analysis demonstrate that airspace route availability is much more limited in China than in the US – flights can only fly through limited air corridors in China, while airlines in the US have more freedom to determine their flight routes.

4.3. Results of air traffic network structure

4.3.1. Trajectory clustering

Fig. 13 shows the trajectory clustering results; the centroids of the operational air routes linking the top 10 airports in China and the US are displayed as black lines. In this case, 100 and 179 air routes are identified in China and the US, respectively, which means that, on average, there are about two air routes per airport pair in China and four per airport pair in the US for the top 10 airports.

The number of clusters and the percent of outliers identified for each airport pair are shown in Figs. 14 and 15. It is evident that more clusters are identified in the US, which means that there more operational air routes are available in the US. Moreover, the percent of outliers is also higher in the US, which indicates that flights do not follow rigid air corridor structures in the US.

4.3.2. Air route merging

After the air route merging procedure, the number of available air routes linking the top 10 airports in China had reduced from 100 to 66, while the number of available air routes linking the top 10 airports in the US had only reduced by 6, which indicates that in China, there are more air routes linking different airport pairs that share the same

<table>
<thead>
<tr>
<th></th>
<th>Class 1: distributed in several clusters</th>
<th>Class 2: concentrated in one cluster</th>
<th>Class 3: dispersed</th>
</tr>
</thead>
<tbody>
<tr>
<td>China</td>
<td>25</td>
<td>14</td>
<td>1</td>
</tr>
<tr>
<td>United States</td>
<td>16</td>
<td>2</td>
<td>27</td>
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</tbody>
</table>

Fig. 11. Modified Ripley’s K-function curves of the flight track distributions in each airport pair.

Fig. 12. Examples of real flight tracks of three distribution types and the corresponding K curves.

Table 3 Classification results of K-function curves.
airspace when compared with the US. The results also indicate that the traditional airport network cannot adequately represent the air transport system in China. The before-and-after comparisons of air routes are shown in Figs. 16 and 17.

4.3.3. Network structure

We quantify the air traffic network structure using three network metrics. The weighted degree centrality is a measure of the strength of airports in the network; the characteristic path length measures the efficiency of air transportation on the network; and the algebraic connectivity reflects the resilience of the air traffic network. In addition, we compare the network metrics of our network based on actual traffic with the traditional airport-based network, which is constructed by simply linking the top 10 airports, without considering operational air routes and traffic. The results are listed in Table 4.

The results show that, when considering the actual air routes, the difference in the air traffic network structure between China and the US is much more significant when compared with the traditional network based on airports alone. The air traffic network can better reveal the reality of airspace structures.

The weighted degree centrality of the air traffic network is larger in the US, which indicates that the node strength is higher. There are about 35 air routes connected to each airport on average, which is about three times that of China. It is much easier for airports in the U.S. air traffic network to reach another airport.

The characteristic path length of the US air traffic network is smaller than in China. Airports in the US are much “closer” to one another due to the greater availability of routes connecting the airports. From air service providers’ points of view, the US network is more powerful in transporting airplanes.

Moreover, the algebraic connectivity of the US is larger. The failure rate of links between airport pairs are much lower because aircraft have more air route choices when cruising the US airspace. The network is therefore more robust and tends to have fewer failures when an abnormality occurs, such as server weather in certain locations, a temporary close-down of an airport, etc.

4.4. Results of network utilization patterns

Based on 30 days’ flight-tracking data, the NTLM is a $720 \times 66$ matrix for China and a $720 \times 173$ matrix for the US, respectively. Fig. 18 shows the heatmaps for the NTLMs of China and the US. The rows depict the 720 h of the month, the columns show the air routes, and the color intensity indicates the traffic load on a particular air route in an hour. Details of the air route index are listed in Appendix B. Visually, China’s network China tends to follow a few major patterns, while the network utilization dynamics of the US are much more complicated.
4.4.1. Identification of network utilization patterns

To identify the different network utilization patterns in the China and US networks, K-means clustering is performed on the rows of each of the two NTLMs. We use the within-sum-of-squares (WSS) metric and implement the elbow method to find a suitable value of $K$ (Kodinariya and Makwana, 2013). As a result, four clusters and seven clusters were identified in China and the US, respectively. Tables 5 and 6 summarize the network utilization pattern represented by each cluster.

In China, there are two major network utilization patterns: Pattern 1 is “nighttime operations with light traffic load” and Pattern 2 is “daytime operations with heavy traffic load”. In addition, two small clusters representing two other patterns were identified. Pattern 3 corresponds to “morning peak hour operations with heavy traffic loads on air routes of PEK-Pearl River Delta Region, CTU-Pearl River Delta Region, and PEK-XIY” and Pattern 4 relates to “special late-night operations with heavy traffic loads on the air routes of PEK-Pearl River Delta Region, Yangtze River Delta Region-Pearl River Delta Region, and PEK-XIY”.

Fig. 19 show the details of the four network utilization patterns in China, including the histograms of the utilization patterns over each hour of the day, the average number of flights per hour on each route, and the detailed network flows. Below is a detailed description of each pattern according to the information shown in Fig. 19.

Pattern 1 “nighttime operations with light traffic load”: Traffic activity is primarily observed during the nighttime and early morning (0–8am). The traffic load across all air routes is relatively light. The air traffic network is basically in an “off” mode.

Pattern 2 “daytime operations with heavy traffic load”: Traffic activity surges between 10 a.m. and 10 p.m. Most of the air routes are heavily loaded with traffic. The entire network can be considered to be in an “on” mode.

Pattern 3 “morning peak hour operations with heavy traffic loads on air routes of PEK-Pearl River Delta Region, CTU-Pearl River Delta Region, and PEK-XIY”: heavy traffic load on a few routes during the morning (6 a.m. and 10 a.m.). This can be viewed as a special operating mode of the system.

Pattern 4 “special late-night operations with heavy traffic loads on the air routes of PEK-Pearl River Delta Region, Yangtze River Delta Region-Pearl River Delta Region, and PEK-XIY”: heavy traffic on some routes between 0 a.m. and 2 a.m. This could be night cargo traffic or passenger traffic that absorbs the delays accumulated during the daytime. It can be viewed as another special operating mode of the system.

When compared with China, it is evident that network utilization is much more complex in the US. Although seven patterns corresponding to seven clusters are identified, the operational characteristics of the seven patterns are not that distinctive, as shown in Table 6. The diversity of different operational patterns over the entire national air traffic network...
can be hardly captured by clustering analysis on a month’s worth of data. We pick three relatively distinctive patterns and show them in Fig. 20. The three patterns are Pattern 1 “nighttime operations”, Pattern 3 “daytime operations”, and Pattern 6 “evening peak hour operations”.

Overall, the results of the network utilization analysis reveal that both the structure and dynamics of the air traffic network are relatively simple in China. Fewer routes and fewer utilization patterns were identified, meaning that the network in China was either “full” or “empty” for most of the time. By contrast, the air traffic network in the US is much more complicated, as it demonstrates variable structure and utilization patterns, depending on many factors, such as weather, traffic demand, and capacity allocation.

5. Conclusion

The availability of large-scale aircraft tracking data and many other digitalized records of operations have risen new opportunities to characterize an air traffic network in terms of its actual behavior and complexity. In this paper, we proposed a novel framework to quantify the operational capacity and utilization patterns of an air traffic network in national airspace using ADS-B data. Several novel statistical measures and data analytic techniques are integrated in this framework. A case study is implemented based on the framework to analyze and compare the air traffic networks in China and the US. The results reveal that, airspace availability for commercial flights is much more restricted in China, and the network structure is less well connected and less robust, indicating that the operational airspace capacity of China is lower than that of the US. Moreover, air traffic network utilization is less flexible and less diverse in China. China’s air traffic network maintains the same structure and runs with either “full” or “little” traffic loads throughout different hours of a day, while much more diverse operation patterns are identified in the US.

This work can be directly applied in practice to help ANSPs compare their operations worldwide and inform the development of appropriate strategies to improve the capacity and efficiency of an air traffic system. For example, strategies to reduce flight delays in China should consider en-route congestion, if airspace availability cannot be changed in the short term due to social–political constraints. From the perspective of academic research, this work present a new way of constructing an air traffic network model. Compared with the traditional graph theory approach, the proposed data-driven approach extracts features of the network from operational data, rather than assumptions, which makes the finding more meaningful for real-world ATM operations. 

Based upon this work, future work can focus on developing ATM strategies to reduce flight delays utilizing the network features characterized through the data-driven approach. We can apply this work to other network models, such as the one proposed by Péter and Szabó (2012). Moreover, we can built new network flight delay simulation models to explicitly consider the en-route congestions. Lastly, decision support systems can be developed to evaluate and recommend ATM improvement strategies.
Table 5
Network utilization patterns in China.

<table>
<thead>
<tr>
<th>Description</th>
<th># of data points</th>
<th>Avg. # of active routes</th>
<th>Avg. # of flights</th>
</tr>
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<tbody>
<tr>
<td>Pattern 1 Nighttime operations, light traffic load</td>
<td>172</td>
<td>6</td>
<td>8</td>
</tr>
<tr>
<td>Pattern 2 Daytime operations, heavy traffic load</td>
<td>377</td>
<td>36</td>
<td>78</td>
</tr>
<tr>
<td>Pattern 3 Morning peak hour operations, heavy traffic load on certain routes</td>
<td>91</td>
<td>28</td>
<td>63</td>
</tr>
<tr>
<td>Pattern 4 Special late-night operations, heavy traffic load on certain routes</td>
<td>80</td>
<td>22</td>
<td>45</td>
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</tbody>
</table>

Table 6
Network utilization patterns in the US.

<table>
<thead>
<tr>
<th>Description</th>
<th># of data points</th>
<th>Avg. # of active routes</th>
<th>Avg. # of flights</th>
</tr>
</thead>
<tbody>
<tr>
<td>Pattern 1 Nighttime operations, light traffic load</td>
<td>139</td>
<td>12</td>
<td>17</td>
</tr>
<tr>
<td>Pattern 2 Morning peak hour operations, medium traffic load on certain routes</td>
<td>127</td>
<td>22</td>
<td>29</td>
</tr>
<tr>
<td>Pattern 3 Daytime operations, medium traffic load on most routes</td>
<td>108</td>
<td>31</td>
<td>44</td>
</tr>
<tr>
<td>Pattern 4 Noon peak hour operations, medium traffic load on most routes</td>
<td>81</td>
<td>40</td>
<td>62</td>
</tr>
<tr>
<td>Pattern 5 Special day operations, heavy traffic load on certain routes</td>
<td>78</td>
<td>38</td>
<td>61</td>
</tr>
<tr>
<td>Pattern 6 Evening peak hour operations, heavy traffic load</td>
<td>73</td>
<td>52</td>
<td>83</td>
</tr>
<tr>
<td>Pattern 7 Late-night operations, heavy traffic load in western and middle US</td>
<td>114</td>
<td>40</td>
<td>65</td>
</tr>
</tbody>
</table>

Fig. 19. Details of network utilization patterns in China.
Acknowledgments

The work was supported by the Hong Kong Research Grant Council General Research Fund Grant (Project No. 11209717), Early Career Scheme (Project No. 21202716), and the National Natural Science Foundation of China Young Scientists Fund (Project No. 71601166). The authors would like to thank Professor Amedeo Odoni and Professor R. John Hansman at Massachusetts Institute of Technology (MIT) for the insightful discussions and constructive comments that helped to improve this study.

Appendix A

Table 7

<table>
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<td>---------</td>
<td>----------</td>
</tr>
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<td>Beijing</td>
</tr>
<tr>
<td>HKG</td>
<td>Hongkong</td>
</tr>
<tr>
<td>CAN</td>
<td>Guangzhou</td>
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<tr>
<td>PVG</td>
<td>Shanghai</td>
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<td>Chengdu</td>
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<td>HGH</td>
<td>Hangzhou</td>
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<td>SHA</td>
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<tr>
<td>XIY</td>
<td>Xi’an</td>
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<table>
<thead>
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<th>Longitude</th>
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Appendix B

Table 8

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Table 9
Air route index of the US.

<table>
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Appendix C. Supplementary data

Supplementary data related to this article can be found at http://dx.doi.org/10.1016/j.jairtraman.2017.12.005.

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Ball, M., Barnhart, C., Dresner, M., Hansen, M., Neels, K., Odoni, A., Zou, B., 2010. Total


